

III B. Tech II Semester Regular/Supplementary Examinations, May/June -2024**DIGITAL SIGNAL PROCESSING**

(Electronics and Communication Engineering)

Time: 3 hours

Max. Marks: 70

Answer any **FIVE** Questions **ONE** Question from **Each unit**

All Questions Carry Equal Marks

UNIT-I

1. a) What is the condition for stability of an LTI system? [7M]
 b) Find the impulse response $h[n]$ of the system described by the difference equation $8y[n] + 6y[n-1] = x[n]$. [7M]
 (OR)
2. a) What are the conditions for stability and causality of an LTI system? Explain [7M]
 b) For a system described by $8y[n] + 4y[n-1] + y[n-2] = x[n]$ Find the response to a unit amplitude complex sinusoidal excitation at a DT cyclic frequency Ω . [7M]

UNIT-II

3. a) Explain the significance of FFT algorithms. Draw the basic butterfly diagram for radix-2 DIT-FFT. [7M]
 b) Find the DFT of $x[n] = \{0.5, 0.5, 0.5, 0.5, -1, -1, -1, -1\}$ using decimation in time algorithm. [7M]
 (OR)
4. a) What is FFT? How many multiplications and additions are required to compute N point DFT using radix-2 FFT? [7M]
 b) State and prove convolution Properties of DFT. [7M]

UNIT-III

5. a) Compare direct form I and direct form II realization of IIR systems. [7M]
 b) Realize the following IIR system functions in the direct form I and II and also parallel form $H(Z) = 1/(1+aZ^{-1})(1-bZ^{-1})$. [7M]
 (OR)
6. a) With an example explain the design procedure for Butterworth filter. [7M]
 b) Give block diagram representation of linear constant-coefficient difference equations. [7M]

UNIT-IV

7. a) Draw the spectrum of rectangular window function. [7M]
 b) What are the characteristics of linear phase FIR digital filters? [7M]
 (OR)
8. a) Design an FIR digital low pass filter with cutoff frequency 1.2 radian and length $N = 7$. Use frequency sampling method [7M]
 b) What are the characteristics of FIR digital filters? [7M]

UNIT-V

9. a) What is meant by bit reversed addressing mode? What is the application for which this addressing mode is preferred? [7M]
 b) Draw the pipelined MAC configuration to perform convolution operation and explain with neat timing diagrams. [7M]
 (OR)
10. a) What do you mean by circular buffer? [6M]
 b) What are the architectural features of TMS320C5x DSP? [8M]



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UNIT-I

1. a) State the time shifting property of z-transform. [7M]
b) Determine the impulse response of the filter defined by $y(n)=x(n)+by(n-1)$. [7M]
(OR)
2. a) State and prove the properties of convolution. [7M]
b) Give the frequency domain representation of discrete time signals. [7M]

UNIT-II

3. a) Determine IDFT of the following [7M]
(i) $X(k)=\{1,1-j2,-1,1+j2\}$ (ii) $X(k)=\{1,0,1,0\}$
b) Find the DFT of the sequence $x[n]=\{1,2,3,4,5,6,7,8\}$ using DIT FFT. [7M]
(OR)
4. a) How is the FFT algorithm applied to determine inverse discrete Fourier transform? [7M]
b) Derive the equation to implement a butterfly structure In DITFFT algorithm. [7M]

UNIT-III

5. a) Explain the differences between Direct form-I and Direct form-II structures. [7M]
b) What is meant by frequency warping effect? [7M]
(OR)
6. a) What are the basic building blocks of realization structures? [7M]
b) Determine the cascade and parallel realization for the system transfer function $H(z) = 3(Z^2 + 5Z + 4) / (2Z + 1)(Z + 2)$. [7M]

UNIT-IV

7. a) Draw the frequency response of digital low pass and high pass filters. [7M]
b) Explain the frequency-sampling method of FIR filter design with an example. [7M]
(OR)
8. a) What conditions are to be satisfied by the impulse response of an FIR system in order to have a linear phase? [7M]
b) Distinguish between IIR and FIR filters. [7M]

UNIT-V

9. a) What are the special addressing modes of DSP? Explain. [7M]
b) Draw the configuration of a pipelined MAC unit. [7M]
(OR)
10. a) Explain the purpose of six registers used in the TMS320C2X processor. [7M]
b) What are the limitations of pipelining in Digital Signal Processor? [7M]



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UNIT-I

1. a) Explain the frequency response of discrete time system. [7M]
b) Determine the frequency response for the system given by [7M]
 $y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) - x(n-1)$.
 (OR)
2. a) Determine whether the following system given by $y(n) = \log_{10}[\{x(n)\}]$ is [7M]
 Casual or not.
 b) Show that an LTI system can be described by its unit sample response. [7M]

UNIT-II

3. a) Explain the significance of FFT algorithms. Draw the basic butterfly diagram [7M]
 for radix - 2 DIT-FFT.
 b) Find the DFT of $x[n] = \{0.5, 0.5, 0.5, 0.5, -1, -1, -1, -1\}$ using decimation in time [7M]
 algorithm.
 (OR)
4. a) Compute the DFT for the sequence $(0.5, 0.5, 0.5, 0.5, 1, 1, 1, 1)$ using DIF-FFT. [7M]
 b) State and prove convolution Properties of DFT. [7M]

UNIT-III

5. a) Draw the direct form II structure for the given system [7M]
 $y(n) = y(n-1) - \frac{1}{2}y(n-2) + x(n) - x(n-1) + x(n-2)$
 b) Explain Transposed forms. [7M]
 (OR)
6. a) Prove that FIR filter has linear phase if the unit impulse response satisfies the [7M]
 condition $h(n) = h(N-1-n)$, $n=0, 1, \dots, M-1$. Also discuss symmetric and
 antisymmetric cases of FIR filter.
 b) Why IIR filters do not have linear phase? [7M]

UNIT-IV

7. a) Write some examples of multirate digital systems. [7M]
 b) What is a Kaiser window? In what way is it superior to other window [7M]
 functions?
 (OR)
8. a) What is a Hamming window function? Obtain its frequency domain [7M]
 characteristics.
 b) What is the impulse invariant technique? [7M]

UNIT-V

9. a) Describe the multiplier/adder unit of TMS320C54xx processor with a neat [7M]
 block diagram.
 b) What are interrupts? What are the classes of interrupts available in the [7M]
 TMS320C5xx processor?
 (OR)
10. a) Explain the different types of interrupts in TMS320C54xx Processors. [7M]
 b) Describe any four data addressing modes of TMS320C54xx processor. [7M]

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UNIT-I

1.
 - a) State and prove final-value theorem of z-transform. [7M]
 - b) Determine the impulse response of the filter defined by $y(n)=x(n)+by(n-1)$. [7M]

(OR)
2.
 - a) What are the basic elements of a DSP system? Explain. [7M]
 - b) Test the following systems for time invariance $y(n)=n x^2(n)$. [7M]

UNIT-II

3. a) Find the linear convolution of the sequences $x[n] = \{1, 4, 0, 9, -1\}$ and $h[n] = \{-3, -4, 0, 7\}$ [7M]
b) Find the IDFT of $Y(k) = (1, 1, 1, 0)$. [7M]
(OR)
4. a) What are the advantages FFT over DFT. [7M]
b) Find the DFT of the sequence $x[n] = \{1, 2, 1, 2, 1, 2\}$ using decimation in time algorithm. [7M]

UNIT-III

5. a) Obtain the direct form I, direct form II and Cascade form realization of the following system functions. [7M]

$$Y(n) = 0.1 y(n-1) + 0.2 y(n-2) + 3x(n) + 3.6 x(n-1) + 0.6 x(n-2).$$
b) Compare Chebyshev Filter and Butterworth Filter. [7M]
- (OR)
6. a) Obtain direct form I, direct form II and cascade realizations of system described by the equation, $y[n]=y[n-1]-(1/2)y[n-2]+x[n]-x[n-1]+x[n-2]$ [7M]
b) State and prove Parsvel's theorem. [7M]

UNIT-IV

7.
 - a) Explain the need for the use of window sequence in the design of FIR filter. [7M]
Describe the window sequence generally used and compare the properties.
 - b) Draw the indirect form realizations of FIR systems? [7M]

(OR)
8.
 - a) Compare Chebyshev Filter and Butterworth Filter. [7M]
 - b) Explain the impulse invariance method of IIR filter design. [7M]

UNIT-V

9. a) What are the on-chip peripherals of programmable DSP? [7M]
b) Explain the difference between Von Neumann and Harvard architectures. [7M]
Which architecture is preferred for DSP applications and why?
- (OR)
10. a) Explain what is meant by instruction pipelining. [7M]
b) What is the use of MAC unit in DSP architecture? [7M]